



CLASSIFICATION OF DIFFERENTIAL EQUATIONS

Differential Equations	Ordinary	ODE
	Partial	PDE

ODE	Linear (in y and its derivatives)	$y' + A x^2 y = f(x)$
	Non-linear (in y and its derivatives)	$(y')^2 + A y y' = f(x)$

ODE	Homogeneous	$..... = 0$
	Non-homogeneous	$..... = f(x) \neq 0$



System of ODE's	$y' = f(x, y, z)$ $z' = g(x, y, z)$
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ODE	Initial-value Problem	depending on the conditions
	Boundary-value Problem	

PDE's:

Physical Problems	Propagation Problem	open domain
	Equilibrium Problem	closed domain
	Eigenvalue Problem	

Solution Methods	Marching Numerical Method
	Equilibrium Numerical Method



PDE's:

Mathematical Concern	Parabolic	Often a propagation problem
	Elliptic	Often an equilibrium problem
	Hyperbolic	Often an eigenvalue problem



LIPSHITZ CONDITION

Theorem: on existence of a solution for first-order ODE:

$$\frac{dy(t)}{dt} = f(t, y)$$

If $f(t, y)$ is continuous on $a \leq t \leq b$, and there exists a constant L such that

$$|f(t, y) - f(t, z)| \leq L |y - z|$$

for all $t \in [a, b]$, and all real y and z , then the initial-value problem

$$\frac{dy(t)}{dt} = f(t, y) \quad \text{with} \quad y(t_0) = y_0$$

where t_0 in $[a, b]$ possesses a unique solution. This is called Lipschitz condition.



Rudolph Otto Sigismund Lipschitz

German mathematician

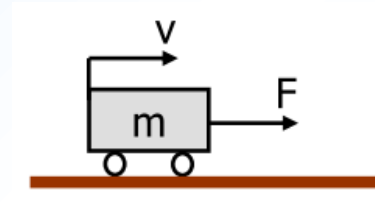
1832 – 1903



Examples of ODE's

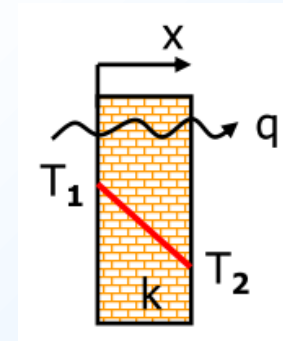
Newton's 2nd law of motion

$$F = m \frac{dv}{dt}$$



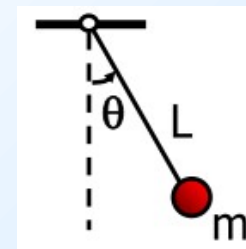
Fourier's law of heat conduction

$$q = -k \frac{dT}{dx}$$



Swinging pendulum

$$\frac{d^2\theta}{dt^2} + \frac{g}{L} \sin(\theta) = 0$$

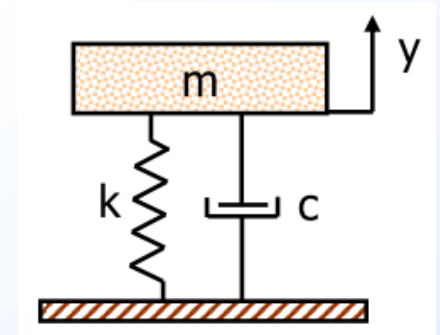




Examples of ODE's

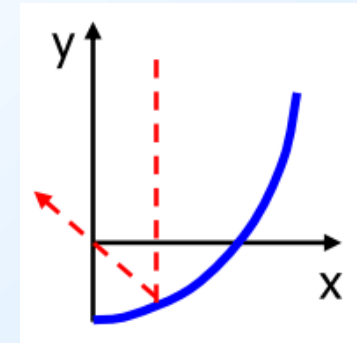
Mass-spring-damper system

$$m \frac{d^2y}{dt^2} + c \frac{dy}{dt} + k y = 0$$



Collector of a solar heater

$$x \left(\frac{dy}{dx} \right)^2 - 2 y \frac{dy}{dx} = 0$$





First-order, Ordinary Differential Equation

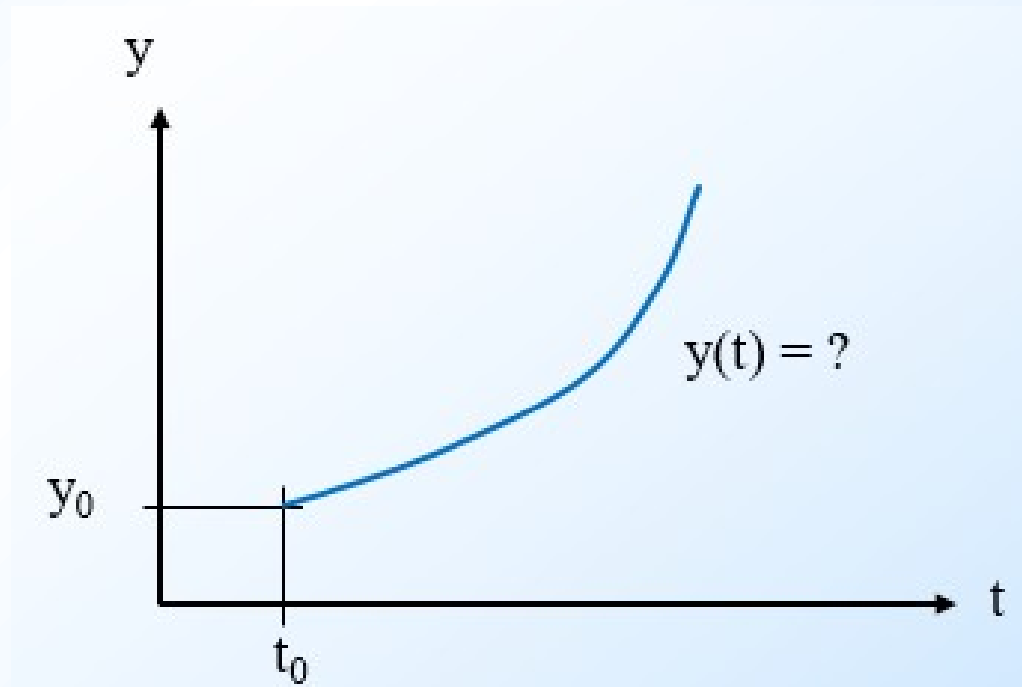
$$\frac{dy(t)}{dt} = f(t,y) \quad , \quad y(t_0) = y_0$$

$$\int_{y_0}^y dy(t) = \int_{t_0}^t f(t,y) dt$$

$$y(t) - y_0 = \int_{t_0}^t f(t,y) dt$$

$$y(t) = y_0 + \int_{t_0}^t f(t,y(t)) dt$$

How to solve?





TAYLOR SERIES

$$\frac{dy(t)}{dt} = f(t, y) \quad , \quad y(t_0) = y_0$$

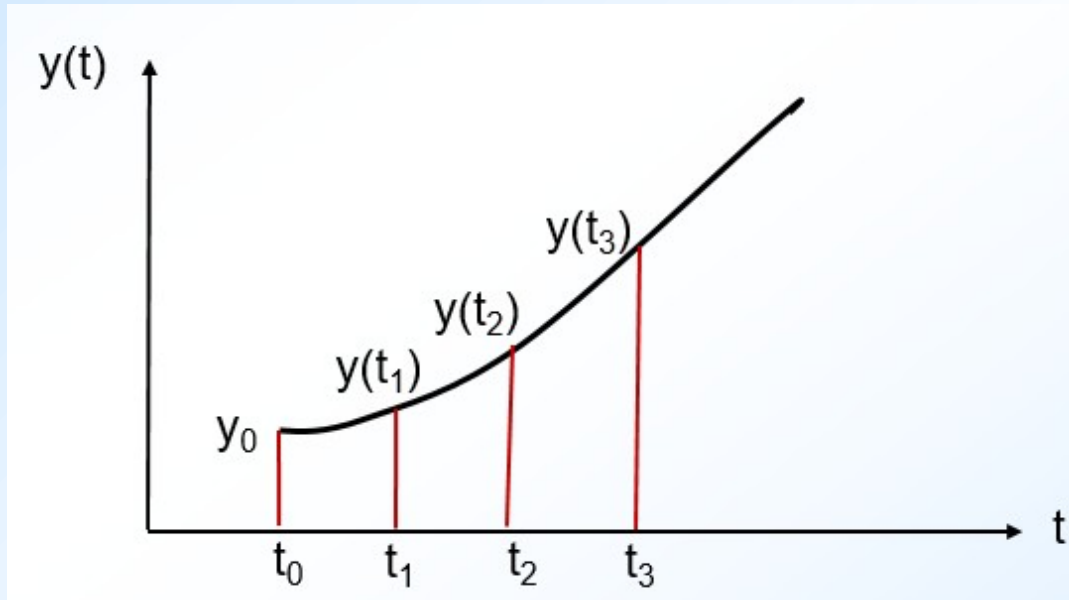
$$y(t) = y(t_0) + (t - t_0) f(t_0, y_0) + \frac{(t - t_0)^2}{2!} y''(t_0) + \dots + \frac{(t - t_0)^{n+1}}{(n+1)!} y^{(n+1)}(\xi)$$

$$y(t_1) = y(t_0) + (t_1 - t_0) f(t_0, y_0) + \frac{(t_1 - t_0)^2}{2!} y''(t_0) + \dots + \frac{(t_1 - t_0)^{n+1}}{(n+1)!} y^{(n+1)}(\xi)$$

$$y(t_2) = y(t_0) + (t_2 - t_0) f(t_0, y_0) + \frac{(t_2 - t_0)^2}{2!} y''(t_0) + \dots + \frac{(t_2 - t_0)^{n+1}}{(n+1)!} y^{(n+1)}(\xi)$$

$$y(t_n) = y(t_0) + (t_n - t_0) f(t_0, y_0) + \frac{(t_n - t_0)^2}{2!} y''(t_0) + \dots + \frac{(t_n - t_0)^{n+1}}{(n+1)!} y^{(n+1)}(\xi)$$

All the y's can be found. But ...



$$y(t_0) = y_0 \quad \text{IC}$$

$$y(t_1) = y_1 = ?$$

$$y(t_2) = y_2 = ?$$

.....

$$y(t_n) = y_n = ?$$

Too much error because t_0 and t_n are too far apart



RUNNING TAYLOR SERIES

$$\frac{dy(t)}{dt} = f(t, y) \quad , \quad y(t_0) = y_0$$

$$y(t) = y(t_0) + (t - t_0) f(t_0, y_0) + \frac{(t - t_0)^2}{2!} y''(t_0) + \dots + \frac{(t - t_0)^{n+1}}{(n+1)!} y^{(n+1)}(\xi)$$

$$y(t_1) = y(t_0) + (t_1 - t_0) f(t_0, y_0) + \frac{(t_1 - t_0)^2}{2!} y''(t_0) + \dots + \frac{(t_1 - t_0)^{n+1}}{(n+1)!} y^{(n+1)}(\xi)$$

$$y(t_2) = y(t_1) + (t_2 - t_1) f(t_1, y_1) + \frac{(t_2 - t_1)^2}{2!} y''(t_1) + \dots + \frac{(t_2 - t_1)^{n+1}}{(n+1)!} y^{(n+1)}(\xi)$$

$$y(t_n) = y(t_{n-1}) + (t_n - t_{n-1}) f(t_{n-1}, y_{n-1}) + \frac{(t_n - t_{n-1})^2}{2!} y''(t_{n-1}) + \dots + \frac{(t_n - t_{n-1})^{n+1}}{(n+1)!} y^{(n+1)}(\xi)$$



RUNNING TAYLOR SERIES

$$\frac{dy(t)}{dt} = f(t, y) \quad , \quad y(t_0) = y_0$$

$$y(t) = y(t_0) + (t - t_0) f(t_0, y_0) + \frac{(t - t_0)^2}{2!} y''(t_0) + \dots + \frac{(t - t_0)^{n+1}}{(n+1)!} y^{(n+1)}(\xi)$$

$$y(t_{n+1}) = y(t_n) + \underbrace{(t_{n+1} - t_n)}_{h} f(t_n, y_n) + \frac{(t_{n+1} - t_n)^2}{2!} y''(t_n) + \dots + \frac{(t_{n+1} - t_n)^{n+1}}{(n+1)!} y^{(n+1)}(\xi)$$


$$y_{n+1} = y_n + h f(t_n, y_n) + \frac{h^2}{2!} y''(t_n) + \dots + \frac{h^{n+1}}{(n+1)!} y^{(n+1)}(\xi)$$

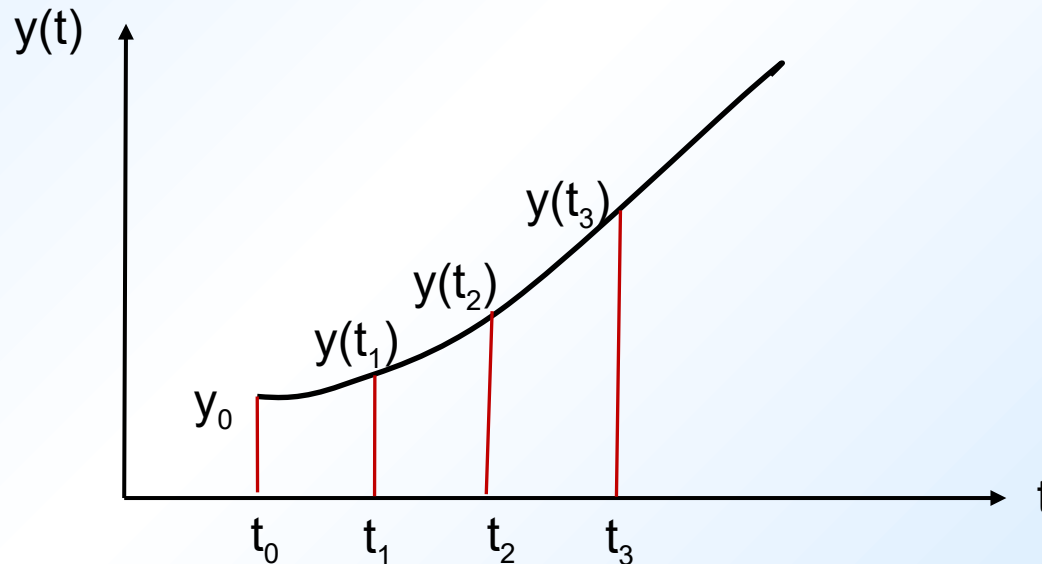
$$y_{n+1} = y_n + h f(t_n, y_n) + \frac{h^2}{2!} \left[\frac{\partial f}{\partial t} + \frac{\partial f}{\partial y} f \right] \bigg|_{t_n, y_n} + \dots + \frac{h^{n+1}}{(n+1)!} y^{(n+1)}(\xi)$$



Given: $\frac{dy(t)}{dt} = f(t, y(t))$, $y(t_0) = y_0$

Question: $y(t) = ?$

Choose $h = \Delta t$ $y(t_1) = ?$, $y(t_2) = ?$, ... , $y(t_n) = ?$



$y(t_0) = y_0$ IC
 $y(t_1) \cong y_1 = ?$
 $y(t_2) \cong y_2 = ?$
...
 $y(t_n) \cong y_n = ?$



Given: $\frac{dy(t)}{dt} = f(t, y(t))$, $y(t_0) = y_0$

$$\int_{y_0}^y dy(t) = \int_{t_0}^t f(t, y(t)) dt$$

$$y(t) - y_0 = \int_{t_0}^t f(t, y(t)) dt \Rightarrow y(t) = y_0 + \underbrace{\int_{t_0}^t f(t, y(t)) dt}_{?}$$

$$y(t_{n+1}) - y(t_n) = \underbrace{\int_{t_n}^{t_{n+1}} f(t, y(t)) dt}_{?} \Rightarrow y_{n+1} = y_n + \int_{t_n}^{t_{n+1}} \underbrace{f(t, y(t))}_{\text{red circle}} dt$$

$$y_{n+1} = y_n + \int_{t_n}^{t_{n+1}} f(t, y(t)) dt \Rightarrow y_{n+1} = y_n + f(t_n, y_n) \underbrace{\int_{t_n}^{t_{n+1}} dt}_{\Delta t = h}$$



Leonhard Euler
Swiss mathematician
1707 - 1783



EULER'S METHOD:

$$y_{n+1} = y_n + h f(t_n, y_n)$$

Local Error:

$$E_{\text{local}} = \frac{h^2}{2!} y''(\xi) \quad , \quad t_{n+1} < \xi < t_n$$

Total or Overall Error:

$$\begin{aligned} E_{\text{total}} &= \sum \frac{h^2}{2!} y''(\xi_n) \\ &= \sum \frac{h}{2!} y''(\xi_n) h \leq \frac{h}{2} \text{Max}(y'') \sum h \\ &\leq \frac{h}{2} \text{Max}(y'') (t_n - t_0) \\ &\propto h^1 \end{aligned}$$

Euler's method is an order 1 method, $O(1)$ or $O(h^1)$, i.e., the overall error is proportional to the first power of the step size, h .



Interpretation of the Euler's method

Given $\frac{dy(t)}{dt} = f(t, y(t))$, $y(t_0) = y_0$ Find $y(t)$

Or, define $h = \Delta t = t_1 - t_0 = t_2 - t_1 = \dots$, and find $y_1 = y(t_1)$, $y_2 = y(t_2)$, ...

Use only the first to terms of the running Taylor series:

$$y_1 = y_0 + h f(t_0, y_0)$$

$$\int_{y_0}^{y_1} dy(t) = \int_{t_0}^{t_1} f(t, y(t)) dt$$

$$y_1 - y_0 \approx f(t_0, y_0) \int_{t_0}^{t_1} dt = h f(t_0, y_0)$$

$$y_1 \approx y_0 + h f(t_0, y_0)$$

$f(t, y)$ is assumed to remain constant at the beginning of the interval

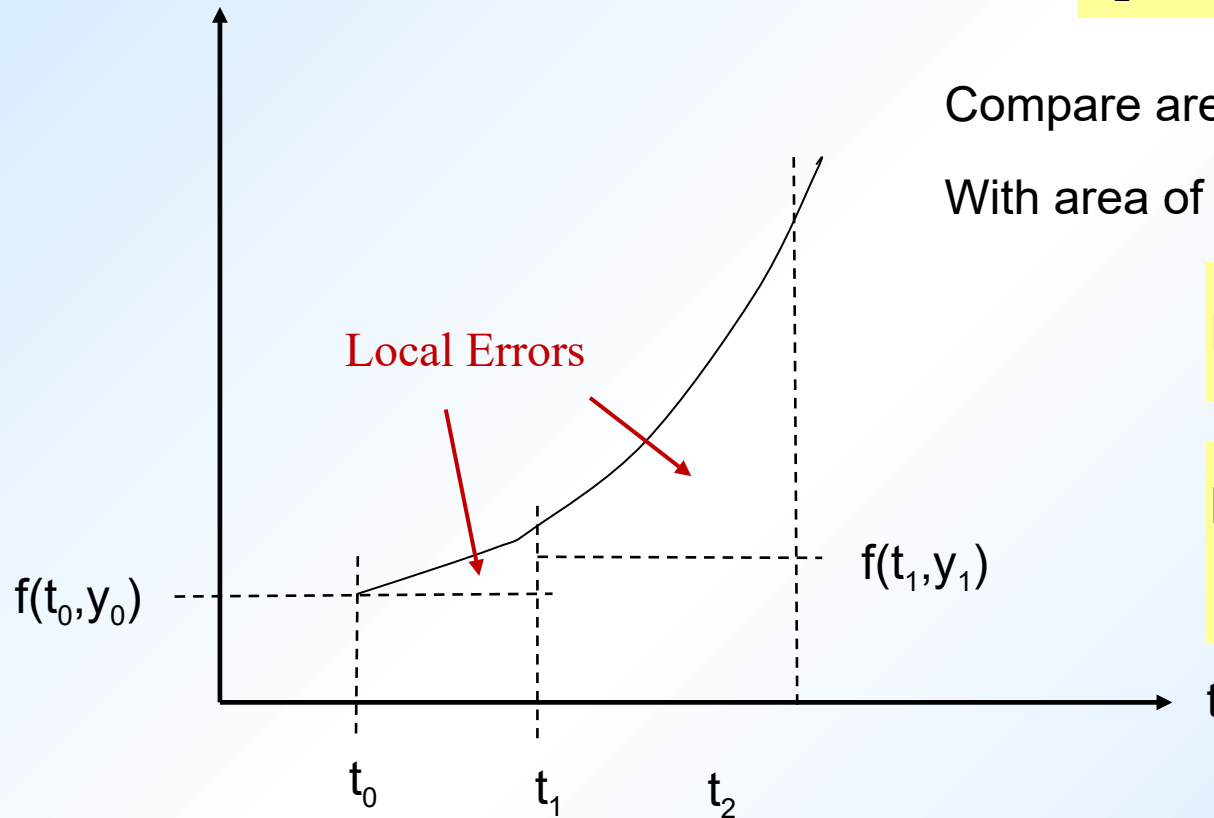
Why at the beginning?



$$y_1 = y_0 + h f(t_0, y_0)$$

$$y_2 = y_1 + h f(t_1, y_1)$$

$$y'(t) = f(t, y)$$

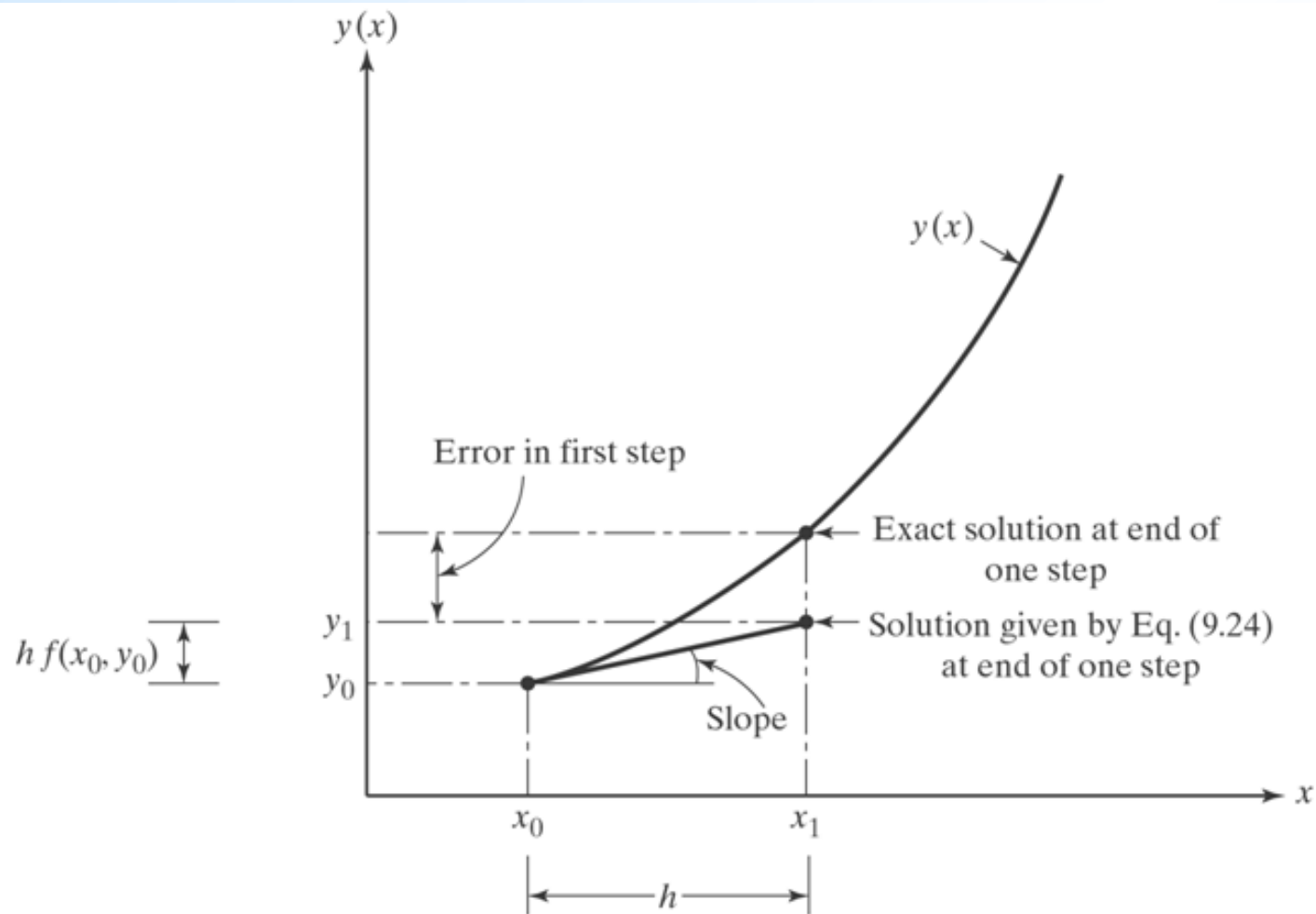


Compare area under the curve (exact)
With area of the rectangle (approximate)

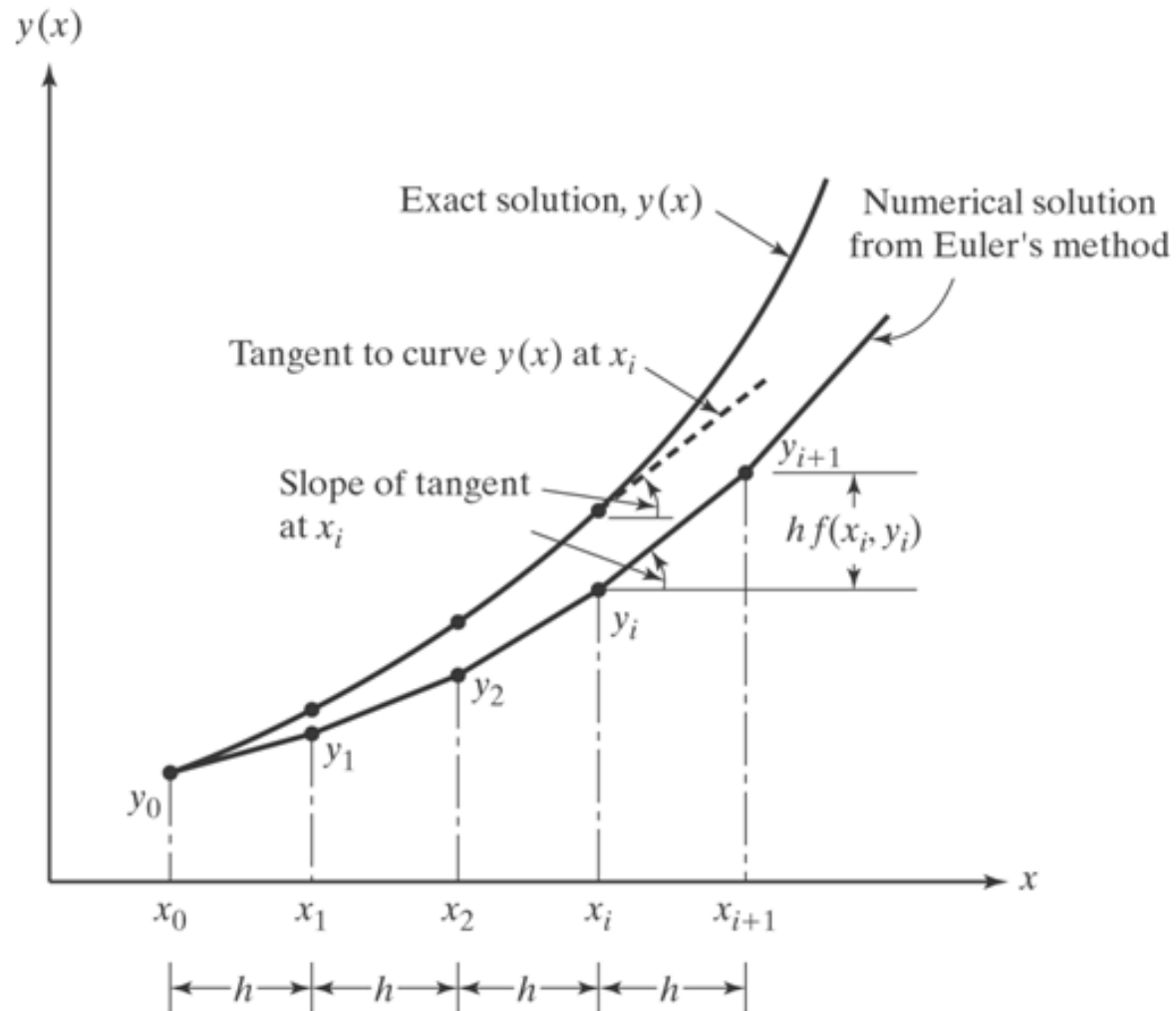
$$E_{\text{total}} = \sum \frac{h^2}{2!} y''(\xi_n)$$

$$E_{\text{total}} \leq \frac{h}{2} \text{Max } (y'') (t_n - t_0)$$
$$\propto h^1$$

$O(1)$ method



Geometrical Interpretation of Euler's method



Accumulation of Error in Euler's method



EXAMPLE ON EULER'S METHOD

$$\frac{dy(t)}{dt} = -a y(t) \quad , \quad y(0) = 1$$

$$y_{\text{exact}} = e^{-at}$$

Euler's Method: $y_{n+1} = y_n + h f(t_n, y_n)$

n	0	1	2	3	4	5	10	100	1000
t / a	0	0.1	0.2	0.3	0.4	0.5	1.0	10.0	100.0
y _{exact}	1	0.905	0.819	0.741	0.670	0.607	0.368	$4.5 \cdot 10^{-5}$	$3.7 \cdot 10^{-44}$
y _{Euler}	1	0.900	0.810	0.729	0.656	0.590	0.349	$2.6 \cdot 10^{-5}$	$1.0 \cdot 10^{-46}$



EXAMPLE ON MODIFICATIONS OF EULER'S METHOD

$$y_{n+1} = y_n + h f \left(t_n + \frac{h}{2}, \frac{y_n + y_{n+1}}{2} \right)$$

$$\frac{dy(t)}{dt} = -a y(t), \quad y(0) = 1$$

$$y_{\text{exact}} = e^{-at}$$

Euler's Method:

$$y_{n+1} = y_n + h f(t_n, y_n)$$

Mod. 1

$$y_{n+1} = y_n + h f(t_{n+1}, y_{n+1})$$

Mod. 2

$$y_{n+1} = y_n + h f \left(t_n + \frac{h}{2}, \frac{y_n + y_{n+1}}{2} \right)$$



EXAMPLE ON MODIFICATIONS OF EULER'S METHOD

n	0	1	2	3	4	5	10	100	1000
t / a	0	0.1	0.2	0.3	0.4	0.5	1.0	10.0	100.0
y_{exact}	1	0.905	0.819	0.741	0.670	0.607	0.368	$4.5 \cdot 10^{-5}$	$3.7 \cdot 10^{-44}$
y_{Euler}	1	0.900	0.810	0.729	0.656	0.590	0.349	$2.6 \cdot 10^{-5}$	$1.0 \cdot 10^{-46}$
y_{end}	1	0.909	0.826	0.751	0.683	0.621	0.386	$7.3 \cdot 10^{-5}$	$4.1 \cdot 10^{-42}$
y_{middle}	1	0.905	0.819	0.741	0.670	0.606	0.368	$4.6 \cdot 10^{-5}$	$3.4 \cdot 10^{-44}$



Runge-Kutta Methods

Taylor Series Order 2:

$$y_{n+1} = y_n + h f(t_n, y_n) + \frac{h^2}{2!} y''(t_n) + R$$

$$y_{n+1} = y_n + h f(t_n, y_n) + \frac{h^2}{2!} \left[\left. \frac{\partial f}{\partial t} \right|_{t_n, y_n} + \left. \frac{\partial f}{\partial y} \right|_{t_n, y_n} f(t_n, y_n) \right] + R$$

$$y_{n+1} = y_n + a h f(t_n, y_n) + b h f(t^*, y^*) + R$$

Runge-Kutta Order 2:

$$t^* = t_n + \alpha h \quad y^* = y_n + \beta h f(t_n, y_n)$$

Find the fractions, a , b , α , and β such that **R's are the same**



Carl David Tolmé Runge

German Scientist

1856 – 1927



Martin Wilhelm Kutta

German Mathematician

1867 – 1944)



Runge-Kutta Methods

$$y_{n+1} = y_n + a h f(t_n, y_n) + b h f\left[\underbrace{t_n + \alpha h}_{t^*}, \underbrace{y_n + \beta h f(t_n, y_n)}_{y^*}\right] + R$$

Expand $f(t^*, y^*)$ in Taylor Series around (t_n, y_n) and substitute

$$f\left[t_n + \alpha h, y_n + \beta h f(t_n, y_n)\right] = f(t_n, y_n) + \alpha h \frac{\partial f}{\partial t} + \beta h f(t_n, y_n) \frac{\partial f}{\partial y} + \dots$$

$$y_{n+1} = y_n + a h f(t_n, y_n) + b h \left[f(t_n, y_n) + \alpha h \frac{\partial f}{\partial t} + \beta h f(t_n, y_n) \frac{\partial f}{\partial y} + \dots \right] + R$$

$$y_{n+1} = y_n + h f(t_n, y_n) + \frac{h^2}{2!} \left[\left. \frac{\partial f}{\partial t} \right|_{t_n, y_n} + \left. \frac{\partial f}{\partial y} \right|_{t_n, y_n} f(t_n, y_n) \right] + R$$



$$y_{n+1} = y_n + h f(t_n, y_n) + \frac{h^2}{2!} \left[\left. \frac{\partial f}{\partial t} \right|_{t_n, y_n} + \left. \frac{\partial f}{\partial y} \right|_{t_n, y_n} f(t_n, y_n) \right] + R$$

$$y_{n+1} = y_n + a h f(t_n, y_n) + b h \left[f(t_n, y_n) + \alpha h \frac{\partial f}{\partial t} + \beta h f(t_n, y_n) \frac{\partial f}{\partial y} + \dots \right] + R$$

Equate the coefficients of the same powers of h:

$$\left. \begin{array}{l} \text{For } h^1 : \quad 1 = a + b \\ \text{For } h^2 : \quad \frac{1}{2} = b \alpha \quad \text{and} \quad \frac{1}{2} = b \beta \end{array} \right\} \begin{array}{l} \text{Choose any one of the unknowns} \\ \text{arbitrarily, That sets the other three} \end{array}$$



2nd Order RUNGE-KUTTA Methods

Euler's Method:

$$y_{n+1} = y_n + h f(t_n, y_n)$$

1st Order

Heun's Method

$$y_{n+1} = y_n + \frac{h}{2} \left[f(t_n, y_n) + f(t_{n+1}, y_n + h f(t_n, y_n)) \right]$$

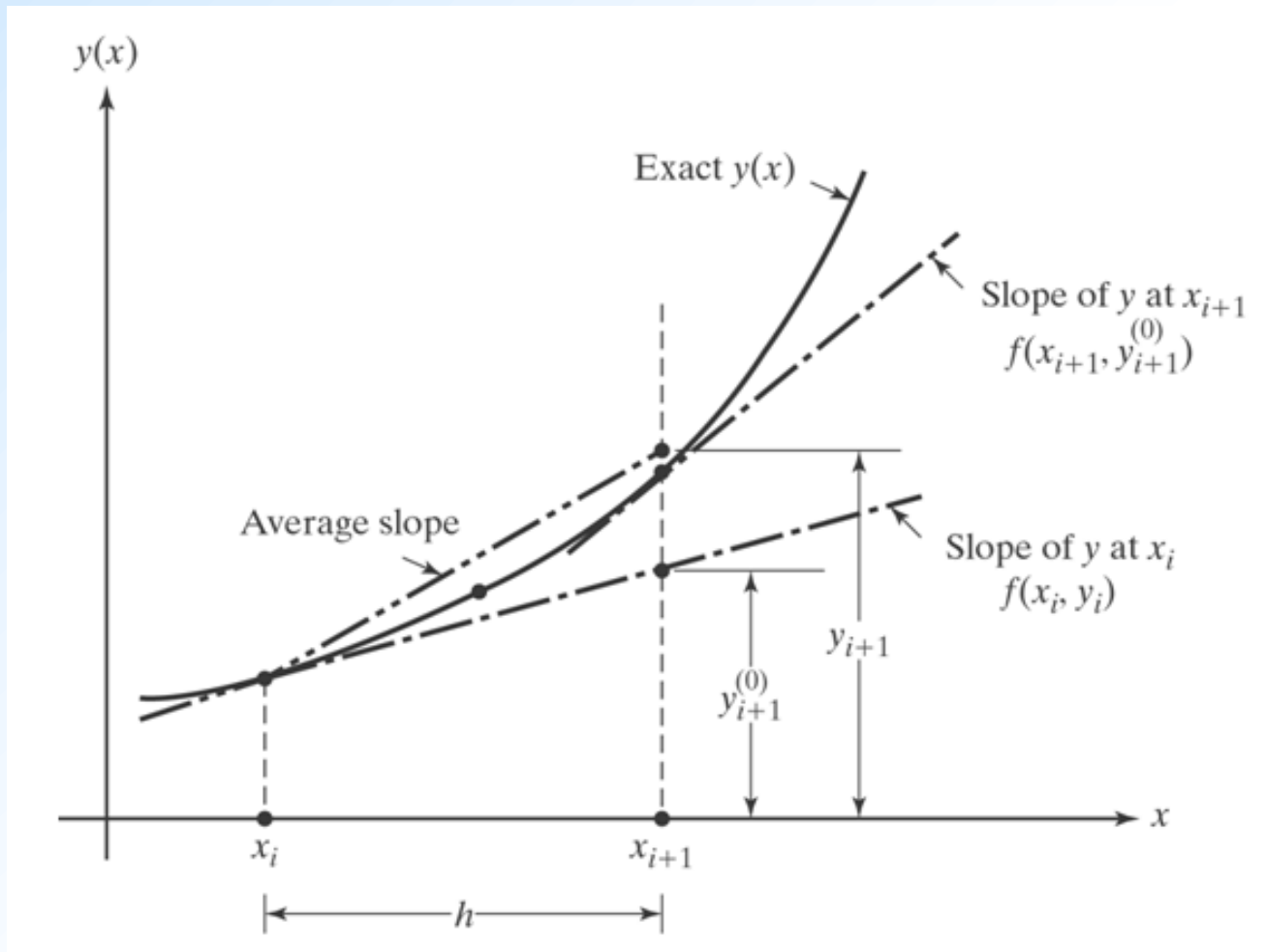
The Modified Euler's Method

$$y_{n+1} = y_n + h \left[f\left(t_n + \frac{h}{2}, y_n + \frac{h}{2} f(t_n, y_n)\right) \right]$$

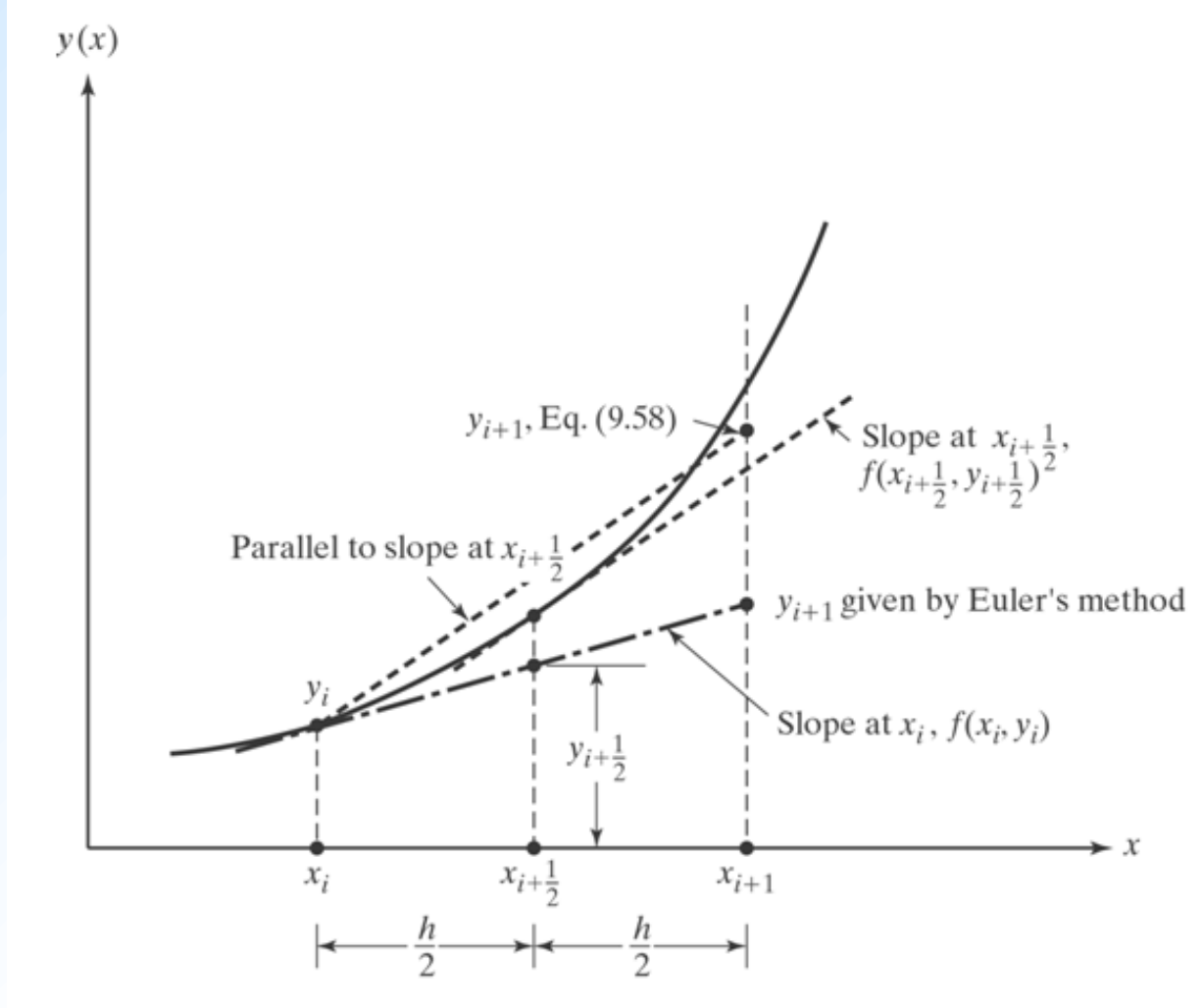


Karl Heun

German Mathematician
1859 - 1929



Geometrical Interpretation of Heun's method



Geometrical Interpretation of the Modified Euler's method



Running Taylor Series:

$$y_{n+1} = y_n + h y'(t_n) + \frac{h^2}{2!} y''(t_n) + \frac{h^3}{3!} y'''(t_n) + \frac{h^4}{4!} y^{(4)}(t_n) + \underbrace{\frac{h^5}{5!} y^{(5)}(\xi)}$$

Runge-Kutta order 4:

$$y_{n+1} = y_n + a h f(t_n, y_n) + b h f(t_n^*, y_n^*) + c h f(t_n^{**}, y_n^{**}) + c h f(t_n^{***}, y_n^{***}) + \underbrace{\frac{h^5}{5!} y^{(5)}(\xi)}_{\text{Local Error}}$$

$$t_n^* = t_n + \alpha h$$

$$y_n^* = y_n + \beta h f(t_n, y_n)$$

$$t_n^{**} = t_n + \gamma h$$

$$y_n^{**} = y_n + \eta h f(t_n, y_n)$$

$$t_n^{***} = t_n + \nu h$$

$$y_n^{***} = y_n + \varepsilon h f(t_n, y_n)$$

10 unknowns

Equate the coefficients
of the same powers of h

9 relations



Fourth-Order Runge-Kutta Methods

Method Attributed to Runge:

$$y_{n+1} = y_n + \frac{h}{6} (K_1 + 2 K_2 + 2 K_3 + K_4)$$

$$K_1 = f(t_n, y_n)$$

$$K_2 = f\left(t_n + \frac{h}{2}, y_n + \frac{h}{2} K_1\right)$$

$$K_3 = f\left(t_n + \frac{h}{2}, y_n + \frac{h}{2} K_2\right)$$

$$K_4 = f(t_n + h, y_n + h K_3)$$

This method reduces to Simpson's one-third rule when $f(t, y) = f(t)$.



Method Attributed to Kutta:

$$y_{n+1} = y_n + \frac{h}{8} (K_1 + 3 K_2 + 3 K_3 + K_4)$$

$$K_1 = f(t_n, y_n)$$

$$K_2 = f\left(t_n + \frac{h}{3}, y_n + \frac{h}{3} K_1\right)$$

$$K_3 = f\left(t_n + \frac{2h}{3}, y_n - \frac{h}{3} K_1 + h K_2\right)$$

$$K_4 = f(t_n + h, y_n + h K_1 - h K_2 + h K_3)$$

This method reduces to Simpson's 3/8 rule when $f(t, y) = f(t)$.



Runge-Kutta-Gill Method:

$$y_{n+1} = y_n + \frac{h}{6} \left(K_1 + 2 \left(1 - \frac{1}{\sqrt{2}} \right) K_2 + 2 \left(1 + \frac{1}{\sqrt{2}} \right) K_3 + K_4 \right)$$

$$K_1 = f(t_n, y_n)$$

$$K_2 = f \left(t_n + \frac{h}{2}, y_n + \frac{h}{2} K_1 \right)$$

$$K_3 = f \left(t_n + \frac{h}{2}, y_n + \left(-\frac{1}{2} + \frac{1}{\sqrt{2}} \right) h K_1 + \left(1 - \frac{1}{\sqrt{2}} \right) h K_2 \right)$$

$$K_4 = f \left(t_n + h, y_n - \frac{1}{\sqrt{2}} h K_2 + \left(1 + \frac{1}{\sqrt{2}} \right) h K_3 \right)$$

This is one of the most widely used fourth-order methods. The constants are selected to reduce the amount of storage required in the solution of a large number of simultaneous first-order differential equations.



EXAMPLE ON RUNGE-KUTTA METHODS

Euler's Method:

$$y_{n+1} = y_n + h f(t_n, y_n)$$

Heun's Method

$$y_{n+1} = y_n + \frac{h}{2} [f(t_n, y_n) + f(t_{n+1}, y_n + f(t_n, y_n))]$$

The Runge-Kutta Order 4

$$y_{n+1} = y_n + \frac{h}{6} (K_1 + 2 K_2 + 2 K_3 + K_4)$$

$$K_1 = f(t_n, y_n)$$

$$K_2 = f\left(t_n + \frac{h}{2}, y_n + \frac{h}{2} K_1\right)$$

$$K_3 = f\left(t_n + \frac{h}{2}, y_n + \frac{h}{2} K_2\right)$$

$$K_4 = f(t_{n+1}, y_n + h K_3)$$



$$\frac{d y(t)}{d t} = -a y(t) \quad , \quad y(0) = 1$$

$$y_{\text{exact}} = e^{-a t}$$

n	0	1	2	3	4	5	10	100	1000
t / a	0	0.1	0.2	0.3	0.4	0.5	1.0	10.0	100.0
y _{exact}	1	0.90484	0.81873	0.74082	0.67032	0.60653	0.36788	4.54 10 ⁻⁵	3.72 10 ⁻⁴⁴
y _{Euler}	1	0.900	0.810	0.729	0.656	0.590	0.349	2.6 10 ⁻⁵	1.0 10 ⁻⁴⁶
y _{R-K 2}	1	0.905	0.819	0.741	0.671	0.607	0.369	4.6 10 ⁻⁵	4.45 10 ⁻⁴⁴
y _{R-K 4}	1	0.90484	0.81873	0.74082	0.67032	0.60653	0.36788	4.54 10 ⁻⁵	3.72 10 ⁻⁴⁴



RUNGE-KUTTA METHODS

Euler's Method:

$$y_{n+1} = y_n + h f(t_n, y_n)$$

Heun's Method

$$y_{n+1} = y_n + \frac{h}{2} [f(t_n, y_n) + f(t_{n+1}, y_n + f(t_n, y_n))]$$

The Runge-Kutta Order 4

$$y_{n+1} = y_n + \frac{h}{6} (K_1 + 2 K_2 + 2 K_3 + K_4)$$

$$K_1 = f(t_n, y_n)$$

$$K_2 = f\left(t_n + \frac{h}{2}, y_n + \frac{h}{2} K_1\right)$$

$$K_3 = f\left(t_n + \frac{h}{2}, y_n + \frac{h}{2} K_2\right)$$

$$K_4 = f(t_{n+1}, y_n + h K_3)$$

h or Δt

1. How to choose?
2. Why constant and uniform?



STABILITY OF RUNGE-KUTTA METHODS

$$\frac{dy}{dt} = \lambda y \quad \text{IC: } y(0) = 1$$

Exact Solution:

$$y(t) = e^{\lambda t}$$

Numerical Solution:

$$y_{n+1} = y_n P(\lambda h)$$

Euler's Method

$$y_{n+1} = y_n (1 + \lambda h)$$

Runge-Kutta Order 2

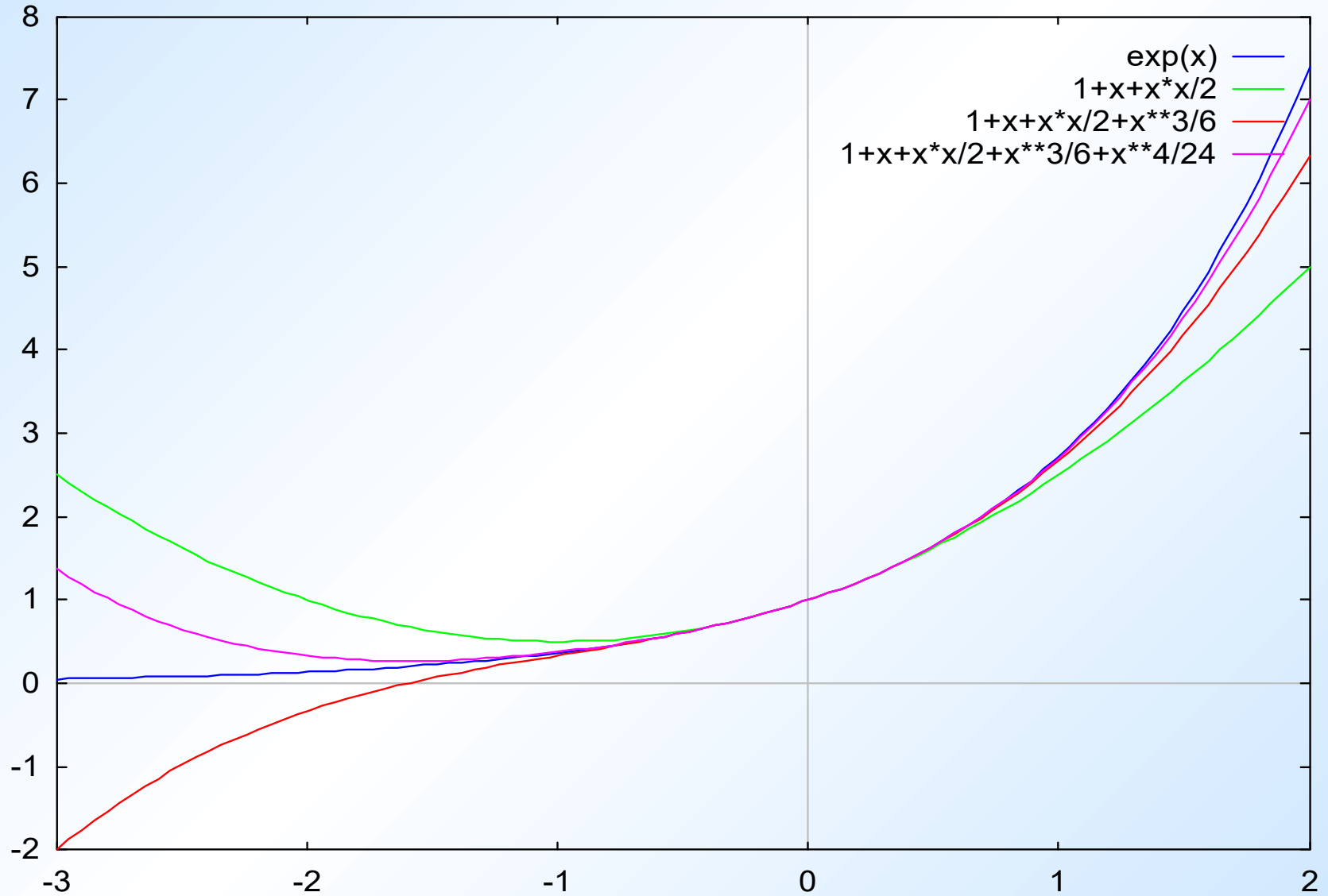
$$y_{n+1} = y_n \left(1 + \lambda h + \frac{(\lambda h)^2}{2} \right)$$

Runge-Kutta Order 4

$$y_{n+1} = y_n \left(1 + \lambda h + \frac{(\lambda h)^2}{2} + \frac{(\lambda h)^3}{3!} + \frac{(\lambda h)^4}{4!} \right)$$



ME – 510 NUMERICAL METHODS FOR ME II





EXAMPLE ON STABILITY OF RUNGE-KUTTA METHODS

Given:

$$\frac{dy}{dt} = 10y - 10t - 1$$

General Solution

$$y(t) = A e^{10t} - t$$

Initial Condition

$$y(0) = 0$$

Exact Solution:

$$y(t) = -t, \quad A \equiv 0$$



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t	Exact	Runge-Kutta Order 4		
		h = 0.01		
0.2	- 0.2	- 0.2		
0.4	- 0.4	- 0.39998		
0.6	- 0.6	- 0.59986		
0.8	- 0.8	- 0.79896		
1.0	- 1.0	- 0.99232		
1.2	- 1.2	- 0.11134		
1.4	- 1.4	- 0.98318		
1.6	- 1.6	1.4702		
1.8	- 1.8	20.815		
2.0	- 2.0	164.59		



t	Exact	Runge-Kutta Order 4		
		h = 0.01	h = 0.001	
0.2	- 0.2	- 0.2	- 0.19998	
0.4	- 0.4	- 0.39998	- 0.39988	
0.6	- 0.6	- 0.59986	- 0.59918	
0.8	- 0.8	- 0.79896	- 0.79394	
1.0	- 1.0	- 0.99232	- 0.95529	
1.2	- 1.2	- 0.11134	- 0.86994	
1.4	- 1.4	- 0.98318	1.0378	
1.6	- 1.6	1.4702	16.410	
1.8	- 1.8	20.815	131.26	
2.0	- 2.0	164.59	981.07	



ME – 510 NUMERICAL METHODS FOR ME II

t	Exact	Runge-Kutta Order 4		
		h = 0.01	h = 0.001	h = 0.0001
0.2	- 0.2	- 0.2	- 0.19998	- 0.19986
0.4	- 0.4	- 0.39998	- 0.39988	- 0.39920
0.6	- 0.6	- 0.59986	- 0.59918	- 0.59483
0.8	- 0.8	- 0.79896	- 0.79394	- 0.76311
1.0	- 1.0	- 0.99232	- 0.95529	- 0.72925
1.2	- 1.2	- 0.11134	- 0.86994	0.79465
1.4	- 1.4	- 0.98318	1.0378	13.316
1.6	- 1.6	1.4702	16.410	107.03
1.8	- 1.8	20.815	131.26	800.08
2.0	- 2.0	164.59	981.07	5921.3

